

### 18.118, SPRING 2022, PROBLEM SET 3

Review/useful information:

- Lie group  $\mathrm{SL}(2, \mathbb{R})$ : consists of  $2 \times 2$  real matrices with determinant 1.
- $\mathrm{PSL}(2, \mathbb{R})$ : the quotient of  $\mathrm{SL}(2, \mathbb{R})$  by the central subgroup  $\{I, -I\}$  where  $I$  denotes the identity matrix.
- Lie algebra  $\mathfrak{sl}(2, \mathbb{R})$ : consists of  $2 \times 2$  real matrices with trace 0. Note that  $\mathfrak{sl}(2, \mathbb{R})$  is the tangent space to  $\mathrm{SL}(2, \mathbb{R})$  (and thus to  $\mathrm{PSL}(2, \mathbb{R})$ ) at the identity. Also, if  $\mathbf{a} \in \mathfrak{sl}(2, \mathbb{R})$ , then the matrix exponential  $\exp(\mathbf{a})$  lies in  $\mathrm{SL}(2, \mathbb{R})$  and can also be viewed as an element of  $\mathrm{PSL}(2, \mathbb{R})$ .
- For  $A \in \mathrm{PSL}(2, \mathbb{R})$ , denote by  $L_A : \mathrm{PSL}(2, \mathbb{R}) \rightarrow \mathrm{PSL}(2, \mathbb{R})$  the left multiplication by  $A$ :  $L_A(B) = AB$ .
- For  $\mathbf{a} \in \mathfrak{sl}(2, \mathbb{R})$ , define the vector field  $Z_{\mathbf{a}}$  on  $\mathrm{PSL}(2, \mathbb{R})$  by

$$Z_{\mathbf{a}}(A) = dL_A(I)\mathbf{a} \in T_A \mathrm{PSL}(2, \mathbb{R}).$$

Note that  $Z_{\mathbf{a}}$  is *left-invariant*, that is

$$dL_A(B)Z_{\mathbf{a}}(B) = Z_{\mathbf{a}}(L_A(B)).$$

- The flow  $e^{tZ_{\mathbf{a}}} : \mathrm{PSL}(2, \mathbb{R}) \rightarrow \mathrm{PSL}(2, \mathbb{R})$  is the right multiplication by matrix exponential:

$$e^{tZ_{\mathbf{a}}}(A) = A \exp(t\mathbf{a}) \quad \text{for all } A \in \mathrm{PSL}(2, \mathbb{R}), \quad \mathbf{a} \in \mathfrak{sl}(2, \mathbb{R}). \quad (1)$$

- Pushforward of left-invariant vector fields by the flows of left-invariant vector fields: if  $\mathbf{a}, \mathbf{b} \in \mathfrak{sl}(2, \mathbb{R})$  and  $A \in \mathrm{PSL}(2, \mathbb{R})$  then

$$de^{tZ_{\mathbf{a}}}(A)Z_{\mathbf{b}}(A) = Z_{\mathbf{c}}(e^{tZ_{\mathbf{a}}}(A)) \quad \text{where } \mathbf{c} = \exp(-t\mathbf{a})\mathbf{b}\exp(t\mathbf{a}) \in \mathfrak{sl}(2, \mathbb{R}). \quad (2)$$

- We have the commutation identity

$$[Z_{\mathbf{a}}, Z_{\mathbf{b}}] = Z_{[\mathbf{a}, \mathbf{b}]} \quad \text{for all } \mathbf{a}, \mathbf{b} \in \mathfrak{sl}(2, \mathbb{R}) \quad (3)$$

where the left-hand side is the Lie bracket of the vector fields  $Z_{\mathbf{a}}, Z_{\mathbf{b}}$  on  $\mathrm{PSL}(2, \mathbb{R})$  and the right-hand side features the commutator  $[\mathbf{a}, \mathbf{b}] = \mathbf{a}\mathbf{b} - \mathbf{b}\mathbf{a}$  of the matrices  $\mathbf{a}, \mathbf{b}$ .

- Poincaré upper half-plane model for the hyperbolic plane:

$$\mathbb{H}^2 = \{z \in \mathbb{C} \mid \mathrm{Im} z > 0\}, \quad g = \frac{|dz|^2}{(\mathrm{Im} z)^2}.$$

- Action of  $\mathrm{SL}(2, \mathbb{R})$  on  $\mathbb{H}^2$ :

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \mathrm{SL}(2, \mathbb{R}) \implies \gamma_A(z) = \frac{az + b}{cz + d}.$$

Acts on the left (i.e.  $\gamma_{AB} = \gamma_A \circ \gamma_B$ ) by isometries and descends to  $\mathrm{PSL}(2, \mathbb{R})$ . Also defines the natural (left) action on the sphere bundle  $S\mathbb{H}^2$ :

$$(z, v) \in S\mathbb{H}^2 \implies \tilde{\gamma}_A(z, v) = (\gamma_A(z), \gamma'_A(z)v)$$

where  $\gamma'_A(z) \in \mathbb{C}$  is the derivative of  $\gamma_A(z)$  as a complex analytic function of  $z$ , which can be computed to be

$$\gamma'_A(z) = \frac{1}{(cz + d)^2}.$$

In this problemset we express the vector fields  $V, W, V_\perp, U_+, U_-$  that we introduced on  $S\mathbb{H}^2$  in terms of the Lie algebra of the Lie group

$$G := \mathrm{PSL}(2, \mathbb{R}).$$

(If  $M = \Gamma \backslash \mathbb{H}^2$  is a hyperbolic surface, then one can show that  $SM \simeq \Gamma \backslash G$  is the set of left  $\Gamma$ -cosets on  $G$ . Since the vector fields defined below are left-invariant, they descend to  $SM$ . This gives a Lie algebraic way of thinking about the geodesic and horocyclic flows on hyperbolic surfaces.)

1. The point  $(z, v) = (i, i)$  lies in  $S\mathbb{H}^2$ . Show that the map

$$\Phi : G \rightarrow S\mathbb{H}^2, \quad \Phi(A) = \tilde{\gamma}_A(i, i)$$

is a diffeomorphism. (Hint: injectivity can be checked directly. Bijectivity of the differential can be reduced to the case  $A = I$  because we have a group action. For surjectivity, we need to show that the group  $G$  acts transitively on  $S\mathbb{H}^2$ : to do this we can first show that any  $(z, v) \in S\mathbb{H}^2$  can be mapped to  $(i, w)$  for some  $w \in \mathbb{C}$ ,  $|w| = 1$ , and then map  $(i, w)$  to  $(i, i)$  by another element of  $S\mathbb{H}^2$ .)

2. Let  $V, W$  be the vector fields on  $S\mathbb{H}^2$  such that  $e^{tV}$  is the geodesic flow and  $e^{sW}(z, v) = (z, R_s v)$  where  $R_s : T_z\mathbb{H}^2 \rightarrow T_z\mathbb{H}^2$  is the counterclockwise rotation by angle  $s$ ; if we think of  $v$  as an element of  $\mathbb{C} = T_z\mathbb{H}^2$  then  $R_s v = e^{is}v$ .

(a) Explain why the maps  $e^{tV}$  and  $e^{sW}$  commute with the map  $\tilde{\gamma}_A$  for any  $A \in G$ . Show that the pullbacks  $\Phi^*V, \Phi^*W$  are left-invariant vector fields on  $G$  and conclude that

$$\Phi^*V = Z_{\mathbf{v}}, \quad \Phi^*W = Z_{\mathbf{w}} \quad \text{for some } \mathbf{v}, \mathbf{w} \in \mathfrak{sl}(2, \mathbb{R}).$$

(b) Recall the vector fields  $V_\perp := [V, W]$ ,  $U_+ := V_\perp + W$ ,  $U_- := V_\perp - W$  on  $S\mathbb{H}^2$ . Show that

$$\Phi^*V = Z_{\mathbf{v}}, \quad \Phi^*W = Z_{\mathbf{w}}, \quad \Phi^*V_\perp = Z_{\mathbf{v}_\perp}, \quad \Phi^*U_\pm = Z_{\mathbf{u}_\pm} \quad (4)$$

for the following matrices in  $\mathfrak{sl}(2, \mathbb{R})$ :

$$\mathbf{v} = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & -\frac{1}{2} \end{pmatrix}, \quad \mathbf{w} = \begin{pmatrix} 0 & \frac{1}{2} \\ -\frac{1}{2} & 0 \end{pmatrix}, \quad \mathbf{v}_\perp = \begin{pmatrix} 0 & \frac{1}{2} \\ \frac{1}{2} & 0 \end{pmatrix}, \quad \mathbf{u}_+ = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad \mathbf{u}_- = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}.$$

(Hint: for  $V$  and  $W$ , use part (a) and compute  $V$  and  $W$  at the point  $(i, i)$  to find  $\mathbf{v} = (\Phi^*V)(I)$ ,  $\mathbf{w} = (\Phi^*W)(I)$ . You can use the fact that  $\delta(t) = e^t i$  is a geodesic on  $\mathbb{H}^2$ . For  $V_\perp, U_\pm$  use their definitions and (3).)

**3.** (Optional) Assume that  $a, b, a', b', t \in \mathbb{R}$  satisfy

$$ab = e^{-t/2} - 1, \quad a' = e^{-t/2}a, \quad b' = e^{t/2}b.$$

Check that

$$\exp(b\mathbf{u}_-) \exp(a\mathbf{u}_+) = \exp(t\mathbf{v}) \exp(a'\mathbf{u}_+) \exp(b'\mathbf{u}_-). \quad (5)$$

Using (4) and (1), show the following commutation identity for the geodesic and horocycle flows on  $S\mathbb{H}^2$ :

$$e^{aU_+} \circ e^{bU_-} = e^{b'U_-} \circ e^{a'U_+} \circ e^{tV}. \quad (6)$$

**4.** (Optional) Define the differential 3-form  $\omega$  on  $S\mathbb{H}^2$  uniquely by the condition

$$\omega(V, U_+, U_-) = 1 \quad \text{on the entire } S\mathbb{H}^2.$$

Show that it is invariant under the flows  $e^{tV}$  and  $e^{sU_+}$ , namely  $(e^{tV})^*\omega = (e^{sU_+})^*\omega = \omega$ . (Hint: you can use the definition of pullback of a differential form together with Exercise 2 and the pushforward formula (2).) (One can similarly show invariance under  $e^{sU_-}$ . The volume form  $\omega$  gives the Liouville measure and this exercise shows that the Liouville measure is invariant under the geodesic flow and the horocycle flows.)